

Graphing Vectors, Lines, and Planes with *Mathematica*

Don't forget to press **Shift-Enter** to execute each part. Watch out for upper- and lower-case.

Creating and Graphing Vectors

Define vector $\mathbf{v} = \langle 0, 2, 1 \rangle$ by typing and executing `v={0,2,1}`

Define vector $\mathbf{u} = \langle 1, 2, -1 \rangle$ the same way.

To graph vector \mathbf{v} , we are going to graph it as a short line. Let's use $P(1, 1, 1)$ as our initial point.

The line through P in the direction of \mathbf{v} in parametric form is: $x = 1, y = 2t + 1, z = t + 1$

To graph this, type and execute: `ParametricPlot3D[{1,2t+1,t+1},{t,0,1}]`

Since we will want to look at this graph later, go back and name it by typing `vGraph=` in front of it and re-execute. Do the same thing for vector \mathbf{u} and call it `uGraph`.

To find the normal vector type and execute: `Cross[u,v]`. Graph this vector and call it `nGraph`.

To see all of the vectors together use `Show[vGraph,uGraph,nGraph]`.

If you want to be able to rotate the graph, type and execute `<<RealTime3D`` (note the backwards apostrophe). Nothing will seem to happen. Re-execute the `Show` command. Click and drag over the image to rotate it. Use `Ctrl` while dragging to zoom.

Creating and Graphing a Plane

The easiest way to create the graph of a 3D surface is to use the command

`Plot3D[f(x,y),{x,xmin,xmax},{y,ymin,ymax}]` where $f(x,y)$ is the stuff that z equals.

For example, to graph the circular paraboloid $z = x^2 + y^2$, type and execute:

`Plot3D[x^2+y^2,{x,-4,4},{y,-4,4}]` (Why doesn't it look round?)

Therefore, sometimes we have to solve for z before graphing. We can use *Mathematica* for the algebra:

Type and execute `Solve[3x+5y==0,y]` and observe what happens. (Note the double =)

Back to our vectors \mathbf{u} and \mathbf{v} . Type out the equation of the plane containing these two vectors and point P . Use the `Solve` command to solve for z . (Don't forget to use two = signs.)

Now, rather than re-typing this result, highlight and copy the expression *following the arrow*. Type the `Plot3D` command `Plot3D[f(x,y),{x,0,2},{y,0,2},PlotPoints->2]` and paste the expression for z in for $f(x,y)$. `PlotPoints` helps it look better—we only need two points in each direction for a plane. (Note: The domain for x and y places our point $P(1,1,1)$ is at the center.)

Name this graph by typing `plane=` in front of the `Plot3D` command and re-execute it.

Show all of the graphs together using `Show[vGraph,uGraph,nGraph,plane]`.

Graph this in default mode by typing and executing `<<Default3D`` (note the backwards apostrophe).

Nothing seems to happen. Re-execute the `Show` command. Notice now that you have a frame and axes.

To change the view point, go inside the last `]` of the `Show` command and insert a `,` (comma). Now select "3D ViewPoint Selector . . ." from the "Input" menu. Rotate the box to the angle you want to view your graph. Select "Paste" and then re-execute the code. (Triple-click `ViewPoint` to select for changing.)

Exercise: Find the plane that contains the point $(1, 2, 11)$ and the vector $\langle 2, 6, -1 \rangle$ and is orthogonal to the plane $3x - 4y + z = 6$. Graph all three objects to verify your result. (Hint: Graph in RealTime.)